

# Video Packet Scheduling with Stochastic QoS for Cognitive Heterogeneous Networks

Lei Xu, *IEEE Member*, A. Nallanathan *IEEE Fellow*, and Yuwang Yang

**Abstract**—In this paper, a video packet scheduling framework with stochastic quality of service (QoS) is proposed for cognitive heterogeneous networks based on inter-network cooperation. The video packet scheduling is subject to constraints in the available energy at each call for secondary mobile terminal (MT), the time varying channel state information (CSI) at different interfaces, the total interference power, the target call duration, and the video characteristics. The objective function maximizes the minimum lower bound of video quality. In order to solve the above video packet scheduling problem with stochastic QoS guarantee, a video packet scheduling scheme based on forward-auction theory is proposed. Then, the cumulative distribution function (CDF) for video quality is analyzed. Finally, the power allocation scheme to maximize the minimization lower bound of video quality among different secondary MTs is presented. Simulation results demonstrate the proposed video packet scheduling scheme with stochastic QoS requirement improves the video quality for secondary MT significantly.

**Index Terms**—Cognitive heterogeneous networks, video packet scheduling, auction theory, stochastic QoS, inter-network cooperation.

## I. INTRODUCTION

Wireless communication technologies in the fifth generation (5G) mobile communication systems, are growing rapidly [1, 2], which lead to the radio spectrum resource more scarce. Cognitive radio is proposed to improve the spectrum utilization by allowing unlicensed MTs to use licensed frequency band resource [3–7]. Additionally, several international standardization organizations make some drafts for cognitive radio technology, e.g., 802.11 af, 802.19 TG 1, and LTE-U [8–11]. At the same time, video traffic has become very popular in mobile Internet. However, compared to traditional

voice and data traffic, video traffic is still a challenging problem for cognitive wireless networks. This is because the spectral resource in cognitive wireless network is sparse and video traffic needs to consume more radio resource. Hence, different network resources at cognitive heterogeneous networks need to be aggregated to support the video traffic at secondary MT [12].

In order to guarantee the video quality requirement, video packet scheduling technology is very important. So far, the video packet scheduling algorithms at wireless networks are divided into two categories [13–24]. The first category is the video packet scheduling algorithms at homogeneous wireless network [13–22], where the optimization objectives are to maximize the video quality or achieve the higher energy efficiency. The second category is the video packet scheduling algorithms for heterogeneous wireless networks [23, 24], where the packet scheduler determines which video packet is assigned to which radio interface at each MT based on channel state information (CSI)<sup>1</sup>, the available bandwidth resource and the video traffic characteristics.

At homogeneous wireless network, an energy-efficient video packet scheduling policy is proposed for WLAN [13]. In [14], an energy-efficient video packet scheduling algorithm to improve throughput is proposed over WiMAX for video streaming traffic. On the other hand, a joint resource allocation and packet scheduling algorithm for 4G cellular networks is proposed to maximize the video quality [15]. In [16], a joint video packet scheduling and power allocation algorithm over downlink orthogonal division multiple-access (OFDMA) systems is presented to of all MTs under delay-bound constraints. In [17], a cross-layer video packet scheduling algorithm is proposed for minimizing the reconstructed video distortion at each MT to

Lei Xu, and Yuwang Yang are at School of Computer Science and Engineering, Nanjing University of Science and Technology, Nanjing, China (E-mail: xulei\_marcus@126.com).

A. Nallanathan is at Department of Informatics, King’s College London, London WC2R 2LS, U.K. (nallanathan@ieee.org).

<sup>1</sup>In this work, CSI is equal to the channel power gain.

guarantee the fairness among different MTs. In [18], a joint video packet scheduling and playout control framework with the Markov decision process is formulated, and a novel content-aware playout control algorithm is proposed. In [19], a distortion-aware video packet scheduling algorithm over wireless networks is proposed. For cognitive radio networks, a maximum average service rate and optimal packet queue scheduling algorithm is proposed with delay-constrained video communication in Nakagami fading channels [20].

At heterogeneous wireless networks, an energy and content-aware video packet scheduling algorithm with multi-homing technology is proposed, to consider the energy limitation and the required video QoS [24]. In [23], a joint rate control and scalable stream adaptation problem for multiple clients concurrently is formulated, and randomized packet scheduling algorithm is proposed. Although the video packet scheduling problems for heterogeneous wireless networks are investigated in [23, 24], how video traffic with stochastic QoS requirement affects the power allocation and video packet scheduling for cognitive heterogeneous networks needs to be further investigated.

In this paper, we investigate the video transmission framework with stochastic QoS requirement for cognitive heterogeneous wireless networks. Specially, we summarize our contributions as follows: (i) The video packet scheduling problem based on auction theory is formulated to maximize the video quality; (ii) A heuristic packet scheduling scheme is proposed, and a video quality CDF is analyzed; (iii). A power allocation problem is formulated to maximize the minimization lower bound of video quality during the target call duration, and particle swarm optimization (PSO)-based algorithm is proposed to allocate the power among different secondary MTs. Simulation results demonstrate that video scheduling and power allocation algorithms improve the video quality and strike the balance between fairness and stochastic video quality.

The rest of this paper is organized as follows. The system model is described in Sections II. Section III presents the video packet scheduling and the video quality CDF analysis. A power allocation algorithm with stochastic QoS guarantee is given in Section IV. Finally, performance evaluation and conclusions are given in Sections V and VI, respectively. Table I summarizes the important mathematical symbols

Table I  
SUMMARY OF IMPORTANT SYMBOLS.

Symbol	Definition
$\mathcal{F}$	Set of frames
$\mathcal{T}$	Set of timeslots
$\mathcal{N}$	Set of wireless networks
$\mathcal{L}_f$	Set of packets at frame $f$
$\mathcal{A}_l^f$	Set of ancestors for each packet $l_f$
$\mathcal{S}_n^*$	Set of primary BSs in primary network $n$
$\mathcal{S}_n$	Set of secondary BSs in cognitive network $n$
$\mathcal{M}$	Set of secondary MTs in this geographical region
$\mathcal{M}_{ns}$	Set of secondary MTs in cognitive network $n$ BS $s$
$n_0$	Noise power spectral density
$E_m$	Total available energy at MT $m$
$\eta_{nsm}$	Power amplifier coefficient
$N$	Number of cognitive wireless networks
$x_{nsm}^{fl}$	Video packet scheduling decision
$\mathcal{S}_n^*$	Number of primary BSs in primary network $n$
$\mathcal{S}_n$	Number of secondary BSs in cognitive network $n$
$M$	Number of secondary MTs in this geographical region
$M_{ns}$	Number of secondary MTs in cognitive network $n$ BS $s$
$\tilde{T}_c^m$	Upper bound of video call time for secondary MT $m$
$I_{ns}$	Interference threshold for cognitive network $n$ BS $s$
$P_{nsm}$	Power for cognitive network $n$ BS $s$ MT $m$
$B_{nsm}$	Bandwidth for cognitive network $n$ BS $s$ MT $m$
$R_{nsm}$	Rate for cognitive network $n$ BS $s$ MT $m$
$CW_{nsm}$	Capacity for cognitive network $n$ BS $s$ MT $m$
$P_c$	Fixed circuit power for each secondary MT's interface

used in this work.

## II. SYSTEM MODEL

In this section, system model is described firstly. Then, power consumption model and transmission rate model are presented. Finally, packet-level model and call-level model for video traffic are given.

### A. System Description

In this paper, there is a set,  $\mathcal{N} = \{1, 2, \dots, N\}$ , of wireless networks operated by different service providers. In each wireless network, there is a set,  $\mathcal{S}_n = \{1, 2, \dots, S_n\}$ , of secondary base stations (BSs) and a set,  $\mathcal{S}_n^* = \{1, 2, \dots, S_n\}$ , of primary BSs in the geographical region. Since the coverage of secondary BSs for each network is different from each other and different cognitive networks have overlapped coverage in some areas, the geographical region is partitioned into multiple service areas, as shown in Fig. 1. There is a set,  $\mathcal{M} = \{1, 2, \dots, M\}$ , of secondary MTs in the geographical region and  $\mathcal{M}_{ns} = \{1, 2, \dots, M_{ns}\} \in \mathcal{M}$  is a subset of secondary MTs in the coverage area of cognitive network  $n$  BS  $s$ . In the same cognitive network,

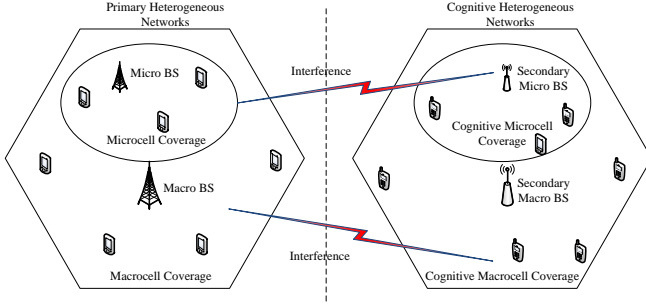


Figure 1. Cognitive heterogeneous networks.

interference mitigation is achieved by interference management schemes [19, 25]. Using inter-network cooperation and multiple radio interfaces, each secondary MT can communicate with multiple secondary BSs simultaneously.

In this work, primary MTs and secondary MTs can share the same spectrum, and the interference power should be controlled to protect the primary MTs' communication. The interference power at each primary BS is controlled with the interference temperature model [26]. Additionally, video traffic transmission is considered [27, 28]. At each time slot, secondary MTs allocate power,  $P_{nsm}^k$ , for cognitive network  $n$  BS  $s$  MT  $m$  at subcarrier  $k$  and video packet scheduling decision,  $x_{nsm}^{fl}$ . If packet  $l$  of frame  $f$  is assigned to cognitive network  $n$  BS  $s$  MT  $m$ ,  $x_{nsm}^{fl} = 1$ ; otherwise,  $x_{nsm}^{fl} = 0$ . The video transmission decision policy on  $P_{nsm}^k$  and  $x_{nsm}^{fl}$  is obtained according to the video traffic characteristics, CSI among different interfaces, and secondary MT total energy constraint. The CSI is unchanged at one time slot and is different from one time slot to another.

### B. Power Consumption and Transmission Rate Model

The power consumption at each interface for each secondary MT has two parts. The first part is a fixed circuit power for each secondary MT's interface and is given by  $P_c$ . The second part is a dynamic part with the digital circuit power consumption and the allocated transmission bandwidth.

$$P_{nsm}^T = \frac{P_{nsm}}{\eta_{nsm}} + P_c \quad (1)$$

where  $P_{nsm}$  is the allocated power for cognitive network  $n$  BS  $s$  to communicate secondary MT

$m$ , and  $\eta_{nsm}$  is the power amplifier coefficient for cognitive network  $n$  BS  $s$  MT  $m$ .

The transmission rate at the physical layer for cognitive network  $n$  BS  $s$  MT  $m$  is

$$R_{nsm} = B_{nsm} \log_2 \left( 1 + \frac{P_{nsm} g_{nsm}}{B_{nsm} n_0 + I_{nsm}} \right). \quad (2)$$

where  $g_{nsm}$  is the channel power gain between secondary MT  $m$  and cognitive network  $n$  BS  $s$ ,  $B_{nsm}$  is the bandwidth for cognitive network  $n$  BS  $s$  MT  $m$ ,  $I_{nsm}$  is the interference power caused by primary MTs for cognitive network  $n$  BS  $s$  MT  $m$ , and  $n_0$  is one-sided spectral density of noise power [29].

### C. Packet-Level Model for Video Traffic

A video bit stream is encoded with a layered video encoder, i.e., a base layer and several enhancement layers are encoded, and each layer is encoded via a group of picture (GoP)<sup>2</sup>. At the same time slot, the data are encoded inter-dependently with estimated motion [26]. However, data with different time slots are encoded independently [33]. Time is divided with time slots,  $\mathcal{T} = \{1, 2, \dots, T\}$ , and the time slot duration,  $\tau$ , is equal. We adopt video call duration to estimate  $T$ . Each time slot contains  $\mathcal{F} = \{1, 2, \dots, F\}$  frames from different layers, and each frame is of I, P, or B type. Each frame contains packets and each packet has the video bit stream at one frame. For example, frame  $f$  contains  $L_f$  packets,  $\mathcal{L}_f = \{1, 2, \dots, L_f\}$ , and each packet has length  $h_f$  bits. In packet-level model for video traffic, some frames are relative to other frames, and these frames exist dependencies. Consequently, decoding video packets at one frame relies on the successful video packet decoding from other frames. The video packets dependencies at different frames are depicted with a directed acyclic graph [24]. Consequently, each packet,  $l_f$ , has a video packet set of ancestors,  $\mathcal{A}_l^f$ . Video packets at  $\mathcal{A}_l^f$  have smaller delay deadline and higher impact than video packet,  $l_f$  [26].

<sup>2</sup>Video coding is an important measurement to improve received video quality with dynamic channel conditions for cognitive heterogeneous networks. Since we focus on the power allocation and video packet scheduling problem with stochastic QoS guarantee, we adopt the layered video encoder, which can be applied to a general one, e.g., H.264/MPEG-4 [30–32], instead of investigating the video coding optimization. The conclusion of our work can be applied to the video coding optimization problem easily.

### D. Call-Level Model for Video Traffic

Assume call arrivals for video traffic follow a Poisson process, and the arrival rate for both new and handoff video calls is  $\lambda$ . Since the most calls for video traffic have a short duration, and a small fraction of calls are a large duration, the video call duration is modeled as a heavy-tailed distribution with hyper-exponential distributions [26]. In this work, a hyper-exponential distribution with two-stage mode is adopted for the call duration, and probability density function (PDF) for the video call duration,  $T_c^m$ , at secondary MT  $m$  is

$$f_{T_c^m}(t) = \frac{a^2}{(a+1)\overline{T}_c^m} e^{-\frac{a}{\overline{T}_c^m}t} + \frac{1}{a(a+1)\overline{T}_c^m} e^{-\frac{1}{a\overline{T}_c^m}t} \quad (3)$$

where  $\overline{T}_c^m$  is the mean, and  $a$  characterizes the micelephant feature [34].

In the service area, the user residence time for the mobility of the secondary MT  $m$  at the service area,  $T_r^m$ , is assumed to be exponential distribution. Additionally, the channel holding time is  $T_h^m = \min(T_c^m, T_r^m)$ , and its PDF is

$$f_{T_h^m}(t) = \frac{a}{(a+1)} \left( \frac{1}{\overline{T}_r^m} + \frac{a}{\overline{T}_c^m} \right) e^{-\left(\frac{1}{\overline{T}_r^m} + \frac{a}{\overline{T}_c^m}\right)t} + \frac{1}{(a+1)} \left( \frac{1}{\overline{T}_r^m} + \frac{1}{a\overline{T}_c^m} \right) e^{-\left(\frac{1}{\overline{T}_r^m} + \frac{1}{a\overline{T}_c^m}\right)t} \quad (4)$$

where  $T_c^m$  and  $T_r^m$  are independent of each other, and  $\overline{T}_r^m$  is the mean for the user resident time, and the derivation of (4) can be obtained in [34].

## III. VIDEO PACKET SCHEDULING AND ANALYSIS

In this section, a video packet scheduling problem is formulated firstly. Then, a video packet scheduling scheme based on auction is proposed. Finally, the CDF for video quality at each secondary MT is analyzed.

### A. Video Packet Scheduling Problem Formulation

In cognitive heterogeneous wireless networks, each secondary MT can utilize radio resource allocation from different cognitive networks to achieve the better performance with the inter-network cooperation technology. The decoder time stamp difference between two consecutive frames for the delay deadline is constant,  $|d_{f+1} - d_f| = \Delta D$ . Additionally, the delay deadline of video packets at the same frame are same. Consequently, the minimum

transmission rate requirement for packet,  $l_f \forall f \in \mathcal{F}$ , is  $r(l_f) = h_f/\Delta D$ . The overall transmission rate requirement for video packet at a radio interface satisfies the achieved transmission rate, i.e.,<sup>3</sup>

$$\sum_{l_f \in \mathcal{L}_f} \sum_{f \in \mathcal{F}} x_{nsm}^{fl} r(l_f) \leq R_{nsm} \quad (5)$$

where  $R_{nsm}$  is the achieved transmission rate for cognitive network  $n$  BS  $s$  MT  $m$ .

With the dependence among different video packets, packets, whose ancestors are not transmitted, are not transmitted, i.e.,

$$x_{nsm}^{fl} \leq x_{n^*s^*m}^{f^*l^*}, \forall l_{f^*}^* \in A_{l_f}^f, l_f \in \bigcup_{f \in \mathcal{F}} \mathcal{L}_f. \quad (6)$$

Additionally, a video packet is assigned to at most one radio interface, i.e.,

$$\sum_{n \in \mathcal{N}} \sum_{s \in \mathcal{S}_n} x_{nsm}^{fl} \leq 1. \quad (7)$$

The optimization framework maximizes the perceived video service quality, which is achieved via video packet scheduling, i.e.,

$$OP1 : \max_{x_{nsm}^{fl}} \left\{ q_m = \frac{\sum_{n \in \mathcal{N}} \sum_{s \in \mathcal{S}_n} \sum_{l_f \in \mathcal{L}_f} \sum_{f \in \mathcal{F}} v_f^l x_{nsm}^{fl}}{\sum_{n \in \mathcal{N}} \sum_{s \in \mathcal{S}_n} \sum_{l_f \in \mathcal{L}_f} \sum_{f \in \mathcal{F}} v_f^l} \right\} \quad (8)$$

$$s.t. (5), (6), (7), x_{nsm}^{fl} \in \{0, 1\}.$$

where  $v_f^l$  is the impact weight of video packet quality for the packet  $l$  at the frame  $f$ . Problem (8) considers the video characteristics based on delay deadlines, distortion impact, video packet dependence, and the CSI for the multiple radio interfaces.

In this formulation, the transmission rate characterizes the capacity for each secondary MT's interference. The packet delay guarantees the quality for each video packet. If the waiting time for a video packet exceeds its maximum delay, it will be dropped. In order to maximize the video transmission quality, we need to reduce the packet loss probability. Therefore, it is necessary to design an efficient video packet scheduling algorithm to reduce the packet loss probability.

<sup>3</sup>If the practical transmission rate of the scheduled video packets at a radio interface is no larger than the maximum transmission rate, we assume the scheduled video packets can be transmitted correctly between the secondary MT and secondary BS; otherwise, we drop the extra video packets with less video quality impact. This assumption makes the joint video packet scheduling and power allocation problem is analyzed conveniently.

## B. Video Packet Scheduling Scheme Based on Auction

In this work, auction theory is a natural way in constructing economic model for video packet scheduling. In the auction model, video packet auctioneer exists to run the auction, determine the winners, optimally assign the resources, and charge the payments. At each secondary MT, each radio interface has a set of subchannels to serve its allocated video packets. At the beginning of this auction, each radio interface at secondary MT submits the total achieved transmission rate to the video packet auctioneer, and each secondary MT sends out its private information including its video packets and its bidding price for each video packet. The video packet auctioneer collects all these sealed-bid information and determines an optimal video packet scheduling scheme. Additionally, the video packet auctioneer calculates the payments and payoffs for video packets and each radio interface.

In this auction model,  $\mathcal{NS}$ , with  $|\mathcal{NS}| = NS$  is a set of radio interfaces,  $\mathcal{CW}_m = \{CW_{nsm}\}, n \in \mathcal{N}, s \in \mathcal{S}_n$  is a set of the auctioned capacity, and  $CW_{nsm} = R_{nsm}\tau$  is the capacity for cognitive network  $n$  BS  $s$  MT  $m$ . Additionally,  $\mathcal{LF}$ , with  $|\mathcal{LF}| = LF$  is a set of video packets,  $r(l_f) = h_f/\Delta D_{f+1,f}$  is a specific transmission rate requirement for each video packet, and  $\Delta D_{f+1,f} = |d_f - d_{f+1}|$  is the delay difference between any two consecutive frames. Video packets at the same frame,  $f$ , have the same delay deadline, denoted by  $d_f$ , and the private valuation for each video packet is  $v_f$ .

Obviously, there is one seller with video packets, radio interfaces are bidders, and the set of bid bundles is  $\mathcal{BW}_m = \{BW_{nsm}\}, n \in \mathcal{N}, s \in \mathcal{S}_n$ . Each bid  $B_{nsm}$  is specified as a 2-tuple  $(d_{nsm}, pv_{nsm})$ , where  $d_{nsm}$  is the transmission rate requirement for each bidder, and  $pv_{nsm}$  is the amount that the bidder is willing to pay for  $d_{nsm}$ . For truthful auction, the bidding price is equal to true valuation. The content-aware packet scheduling (CAPS) is presented in Algorithm 1. In CAPS,  $r_{c_{nsm}}$  is the remaining capacity for cognitive network  $n$  BS  $s$  MT  $m$ ,  $\mathcal{A}_i$  is the  $i$ th group of video packets,  $\mathcal{AV}$  is the distortion impact of video packets, and  $\mathcal{A}$  is the set of the allocated video packets.

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### Algorithm 1 Content-Aware Packet Scheduling (CAPS).

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**Require:** Input  $CW_{nsm}$  and  $l_f, \forall f \in \mathcal{F}$ .

**Ensure:** Output  $x_{nsm}^{fl}$ .

- 1: Secondary MTs advertise video packets  $l_f, \forall l_f \in \mathcal{L}_f, f \in \mathcal{F}$  for auction, and  $r_{c_{nsm}} = R_{nsm}\tau$ .
  - 2: Divide all video packets into different groups, and the video packets with dependence are divided into a group. There are  $AN$  groups.
  - 3: **repeat**
  - 4: Put the first packet of each group into the set  $\mathcal{A} = \{\mathcal{A}_i(1)\}$ , compute  $\mathcal{AV} = \{\mathcal{A}_i(1)v_f^{A_i(1)}\}, i = 1, 2, \dots, AN$ .
  - 5: Secondary MT receives bids  $\mathcal{BW}_m = \{BW_{nsm}\}$  from radio interfaces.
  - 6: Select the video packet,  $(f^*, l^*) = \max_{l_f \in \mathcal{L}_f, f \in \mathcal{F}} \mathcal{AV}$ , with the largest distortion impact. Select the radio interface,  $(n^*, s^*) = \max_{n \in \mathcal{N}, s \in \mathcal{S}_n} r_{c_{nsm}}$ , with the largest remaining capacity.
  - 7: **if**  $r_{c_{n^*s^*m}} - r(l_{f^*}^*) \geq 0$  **then**
  - 8: Set  $x_{n^*s^*m}^{f^*l^*} = 1$ , delete the video packet,  $(f^*, l^*)$ , from the set  $\mathcal{A}, \mathcal{AV}$  and  $\mathcal{A}_i$ . Update the remaining capacity,  $r_{c_{n^*s^*m}} = R_{n^*s^*m}\tau - r(l_{f^*}^*)$ . Go to step 4.
  - 9: **else**
  - 10: Output  $x_{nsm}^{fl}$ .
  - 11: **end if**
  - 12: **until**
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## C. Video Quality CDF

In the subsection, the video quality,  $q_m$ , given the secondary MT transmission rates,  $R_{nsm}$ , at different radio interfaces and frame size  $c_f$  is obtained firstly. Then, using the data rates and packet encoding statistics, the CDF of video quality,  $F_{Q_m}(q_m)$ , is analyzed. With CAPS, the video quality,  $q_m$ , is obtained using transmission rates,  $R_{nsm}$ , and frame size,  $c_f$ .

The set of different video packet encoding and transmission rate combinations resulting in the same video service quality,  $q_m$ , is  $\mathcal{Q}_m$ , and the transmission rate and frame size statistics are mapped into a probability mass function (PMF) for video quality,

i.e.,

$$F_{Q_m}(q_m) = \sum_{Q_m} f_{\mathcal{X}_R}(\mathcal{X}_r) f_{C_I, C_B, C_P}(c_I, c_B, c_P) \quad (9)$$

where  $f_{C_I, C_B, C_P}(c_I, c_B, c_P)$  is the joint PMF for packet encoding at I, B, and P frames with an i.i.d frame size statistics [24],  $\mathcal{X}_R = [R_{11m}, \dots, R_{NS_{Nm}}]$ ,  $\mathcal{X}_r = [r_{11m}, \dots, r_{NS_{Nm}}]$ ,  $\mathcal{X}_B = [B_{11m}, \dots, B_{NS_{Nm}}]$  and  $\mathcal{X}_b = [b_{11m}, \dots, b_{NS_{Nm}}]$ .

For independent fading statistics at different interfaces, the probability about transmission rates,  $r_{11m}^{i_{11m}}, \dots, r_{NS_{Nm}}^{i_{NS_{Nm}}}$ , is

$$f_{\mathcal{X}_R|\mathcal{X}_B}(\mathcal{X}_r) = \sum_{B_m} f_{\mathcal{X}_B}(\mathcal{X}_b) f_{\mathcal{X}_R|\mathcal{X}_B}(\mathcal{X}_r|\mathcal{X}_b) \quad (10)$$

where  $B_m$  is the allocated bandwidth set to secondary MT  $m$ . The conditional probability for transmission rates,  $r_{11m}^{i_{11m}}, \dots, r_{NS_{Nm}}^{i_{NS_{Nm}}}$ , at radio interfaces, given the bandwidth allocation  $B_{11m}, B_{12m}, \dots, B_{NS_{Nm}}$ , is

$$f_{\mathcal{X}_R|\mathcal{X}_B}(\mathcal{X}_r|\mathcal{X}_b) = \prod_{n \in \mathcal{N}, s \in \mathcal{S}_n} f_{R_{nsm}^{i_{nsm}}|B_{nsm}}(r_{nsm}^{i_{nsm}}|b_{nsm}). \quad (11)$$

Given the allocated bandwidth  $B_{nsm}$ , the conditional probability about the transmission rate  $r_{nsm}^{i_{nsm}}$  for cognitive network  $n$  BS  $s$  MT  $m$  is

$$f_{R_{nsm}^{i_{nsm}}|B_{nsm}}(r_{nsm}^{i_{nsm}}|b_{nsm}) = \Pr(\Gamma_{nsm}^{i_{nsm}+1} > \gamma_{nsm} \geq \Gamma_{nsm}^{i_{nsm}}) \quad (12)$$

where the received signal interference to noise rate (SINR),  $\gamma_{nsm}$ , for cognitive network  $n$  BS  $s$  MT  $m$  is an exponential distribution,  $\bar{\gamma}_{nsm} = P_{nsm}\Omega_{nsm}/B_{nsm}n_0$  is the average received SINR for secondary MT  $m$  to communicate with cognitive network  $n$  BS  $s$ ,  $\Omega_{nsm}$  is the average channel power gain for secondary MT  $m$  to communicate with cognitive network  $n$  BS  $s$ , and  $\Gamma_{nsm}^{i_{nsm}}$  is the  $i_{nsm}$ th SINR threshold.

Each radio interface for secondary MT  $m$  can support a discrete transmission rate set,  $r_{nsm}^{i_{nsm}}$ , with  $i_{nsm} \in \{1, \dots, I\}$ . This interface can support transmission rate if the received SINR,  $\gamma_{nsm}$ , at this radio interface exceeds a given threshold,  $\Gamma_{nsm}^{i_{nsm}}$ . The threshold set,  $\Gamma_{nsm}^{i_{nsm}}$ ,  $n \in \mathcal{N}, s \in \mathcal{S}_n, m \in \mathcal{M}, i_{nsm} \in \mathcal{I}$ , is calculated by

$$\Gamma_{nsm}^{i_{nsm}} = 2^{\frac{i_{nsm}}{B_{nsm}}} - 1, i_{nsm} \in \mathcal{I} \quad (13)$$

where  $\Gamma_{nsm}^{I+1}$  is assumed to be  $\infty$ .

#### IV. POWER ALLOCATION WITH STOCHASTIC QoS

In this section, a power allocation problem with maximizing the minimization video quality lower bound is formulated firstly. Then, a power allocation algorithm based on particle swarm optimization is proposed for cognitive heterogeneous networks.

##### A. Power Allocation Problem Formulation

From (10), the probability for the transmission rates,  $R_{nsm}$ , at different interfaces depends on the received average SINR,  $\bar{\gamma}_{nsm}$ . Consequently, the CDF of video quality is a function of the allocated bandwidth and power at different interfaces. The total power consumption for secondary MT  $m$  satisfies the maximum power constraint condition, i.e.,

$$\sum_{n \in \mathcal{N}} \sum_{s \in \mathcal{S}_n} \left( P_c + \frac{P_{nsm}}{\eta_{nsm}} \right) \leq \frac{E_m}{\tilde{T}_c^m} \quad (14)$$

where  $E_m$  is the total available energy at MT  $m$ , and  $\tilde{T}_c^m$  is the upper bound of video call time for secondary MT  $m$ , i.e.,

$$\Pr(T_c^m \leq \tilde{T}_c^m) \geq 1 - \varepsilon_c^m, \varepsilon_c^m \in [0, 1]. \quad (15)$$

where  $\varepsilon_c^m$  is the lower bound of video call time for secondary MT  $m$ .

The interference power at primary BS is limited by

$$E \left( \sum_{m \in \mathcal{M}_{ns}} P_{nsm} h_{nsm}^{\text{PBS}} \right) \leq I_{ns} \quad (16)$$

where  $I_{ns}$  is the interference threshold for primary network  $n$  BS  $s$ , and  $h_{nsm}^{\text{PBS}}$  is the channel power gain between secondary MT  $m$  and primary network  $n$  BS  $s$  with an exponential distribution.

The power allocation strategy adapts to the channel condition to maximize the minimum lower bound of video quality among different secondary MTs under the QoS requirement, i.e.,

$$\begin{aligned} OP2 : & \max_{P_{nsm}} \{ \min q_m \} \\ s.t. : & C1. F_{Q_m}(q_m) \leq \varepsilon_q \\ & C2. (14), (15), P_{nsm} \geq 0. \end{aligned} \quad (17)$$

where  $\varepsilon_q$  is a parameter for the balance between the desired performance and the successful probability of the call transmission.

In this work, we do not consider the combination of  $x_{nsm}^{fl}$  and  $P_{nsm}$  as a target solution. There are

three reasons. First, joint video packet scheduling and power allocation problem is a NP-hard problem. It is difficult to solve the optimal solution. Usually, the original NP-hard problem is divided into sub-problems. Then, the objective functions in (8) and (17) are different. The objective function in (8) maximizes the video quality for secondary MT  $m$  via the video packet scheduling, while the objective function in (17) maximizes the minimization video packet quality among  $M$  secondary MTs. Finally, the video packet scheduling algorithm affects the analysis of video quality CDF. Additionally, the video packet CDF affects the design of power allocation algorithm.

### B. Power Allocation Scheme

The power allocation problem (17) is non-convex optimization problem, and swarm intelligence algorithm can be used to solve it. In swarm intelligence algorithms, PSO is an optimization technique based on the sociological behavior associated with birds flocking. This seeking behavior is an optimization search for solutions to non-linear equations. In PSO, a potential solution in the fitness landscape is called a particle, and a particle representation in swarm is depicted in Fig. 2. In Fig. 2, a particle length is  $M|\mathcal{M}_{ns}|$ , and each particle includes the position vector and the velocity vector. For example, the  $i$ th particle  $\mathcal{X}_i(t) = [x_i^1(t), \dots, x_i^d(t), \dots, x_i^{M|\mathcal{M}_{ns}|}(t)]$  is associated with a velocity vector  $\mathbf{v}_i(t) = [v_i^1(t), \dots, v_i^d(t), \dots, v_i^{M|\mathcal{M}_{ns}|}(t)]$ . Each particle changes its searching direction based on two values during each iteration. The first one is the best searching experience of individual  $\mathcal{X}_{pbest_i}(t)$ . The second one is the best result obtained by any particle in the swarm  $\mathcal{X}_{gbest}(t)$ . When  $\mathcal{X}_{pbest_i}(t)$  and  $\mathcal{X}_{gbest}(t)$  are obtained, the  $i$ th particle updates its velocity and position by (18) and (19).

$$v_i^d(t+1) = \psi(t)v_i^d(t) + \eta_1 r_1 [x_{pbest_i}^d(t) - x_i^d(t)] + \eta_2 r_2 [x_{gbest}^d(t) - x_i^d(t)] \quad (18)$$

and

$$x_i^d(t+1) = x_i^d(t) + v_i^d(t) \quad (19)$$

where  $v_i^d(t+1)$  and  $v_i^d(t)$  are the  $d$ th dimension velocities of particle  $i$  at the  $(t+1)$ th and  $t$ th iterations, respectively.  $x_i^d(t+1)$  and  $x_i^d(t)$  are the

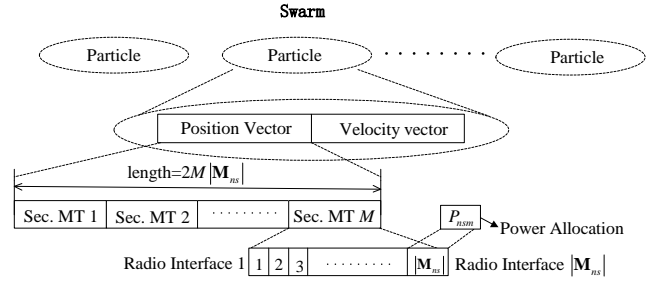


Figure 2. Particle representation in swarm.

$d$ th dimension positions of particle  $i$  at the  $t$ th and  $(t+1)$ th iterations, respectively.  $\mathcal{X}_{pbest_i}(t)$  and  $\mathcal{X}_{gbest}(t)$  are the best position found by particle  $i$  and the best position found by the whole swarm at the  $t$ th iteration, respectively.  $\eta_1$  and  $\eta_2$  are the acceleration constants.  $r_1$  and  $r_2$  are the random numbers generated in the interval  $[0, 1]$ . In (18),  $\psi(t)$  is the inertia weight updated by (20) and (21).

$$\psi(t+1) = \psi(1) + [\psi(T_{\max}) - \psi(1)] \frac{e^{m_i(t)} - 1}{e^{m_i(t)} + 1} \quad (20)$$

and

$$m_i(t) = \frac{f(\mathcal{X}_{pbest_i}(t)) - f(\mathcal{X}_i(t))}{f(\mathcal{X}_{pbest_i}(t)) + f(\mathcal{X}_i(t))} \quad (21)$$

where  $\psi(t+1)$  and  $\psi(t)$  are the inertia weights at the  $(t+1)$ th and  $t$ th iterations, respectively.  $T_{\max}$  is the maximum iteration number and  $m_i(t)$  is the relative improvement function at the  $t$ th iteration. The fitness function for  $\mathcal{X}_i(t)$  is

$$f(\mathcal{X}_i(t)) = \min_{m \in \mathcal{M}} q_m. \quad (22)$$

### C. Computational Complexity

In CAPS, the computational complexity is  $O\left(\sum_{n \in \mathcal{N}} \sum_{s \in \mathcal{S}_n} 3N_{nsm}^P\right)$ .  $N_{nsm}^P$  is the number of allocated video packets for cognitive network  $n$  BS  $s$  MT  $m$ . In PAS, assume  $N_g$  is the total iteration number in PSO,  $N_j^i$  is the cyclic number of the  $j$ th particle at the  $i$ th iteration for generating the feasibility of power allocation, and  $N_p$  is the population number in PSO. Consequently, the total time complexity is  $O\left(\sum_{i=1}^{N_g} \sum_{j=1}^{N_p} 8N_j^i\right)$ .

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**Algorithm 2** Power Allocation Scheme (PAS).
 

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**Require:** Input  $\varepsilon_q$ ,  $B_{ns}$ ,  $E_m$  and  $I_{ns}$ .

**Ensure:** Output  $P_{nsm}$ .

- 1: Generate the initial swarms which satisfy the constraints in (17).
  - 2: **repeat**
  - 3: Calculate the fitness value  $f(\mathcal{X}_i(t))$  of the current position for each particle in swarm.
  - 4: **if**  $f(\mathcal{X}_i(t)) > f(\mathcal{X}_{pbest_i}(t))$  **then**
  - 5:     Set  $\mathcal{X}_{pbest_i}(t) = \mathcal{X}_i(t)$ .
  - 6: **end if**
  - 7: **if**  $f(\mathcal{X}_i(t)) > f(\mathcal{X}_{gbest}(t))$  **then**
  - 8:     Set  $\mathcal{X}_{gbest}(t) = \mathcal{X}_i(t)$ .
  - 9: **end if**
  - 10: Update the position and velocity for each particle. Moreover, update the inertia weight  $\psi(t)$ . Set  $t \leftarrow t + 1$ , and go to step 3.
  - 11: **until**  $t \leq T_{max}$
  - 12: Report  $\mathcal{X}_{gbest}(t)$  as the optimal solution.
- 

## V. PERFORMANCE EVALUATION

This section presents the simulation results for proposed algorithms for video transmission problem with stochastic QoS requirement. We consider a geographical region covered by one cognitive macrocell and one cognitive microcell. The cognitive macrocell has a radius 400 m at the coverage area, while the cognitive microcell has a radius 200 m at the coverage area. Due to the overlapped coverage between cognitive macrocell and cognitive microcell, two service areas can be distinguished and secondary MTs can get service from both cognitive macrocell BS and cognitive microcell BS. The path loss exponent is 4, and the amplitude of multipath fading is Rayleigh. The noise power is  $7 \times 10^{-10}$  watts, and  $I_{nsm}$  follows  $N(0, 1 \times 10^{-11})$  watts. The other simulation parameters are  $\eta_{nsm} = 0.35$ , and  $Q_{nsm} = 10$  mW. The number of secondary MTs in cognitive macrocell and cognitive microcell are 2, respectively. To compare with CAPS+PAS, an earliest deadline first approach (EDFA) is adopted [25]. Video sequences are compressed with an MPEG4-FGS encoder, at 30 fps with the GoP structure. The GoP structure includes 14 frames from one layer. Additionally,  $\tau$  is 466 ms, and the decoder time stamp difference between two successive frames for the delay deadline is  $\Delta D = 40$  ms. The bandwidths of cognitive macrocell and cognitive microcell are

both  $B_{ns} = 4$  MHz. Each packet at video traffic requires a transmission data rate 2 Kbps. The values for video packet distortion impact are  $v_f^l = 4$  for P frames,  $v_f^l = 2$  for B frames, and  $v_f^l = 5$  for I frames [26]. For simplicity, the parameters for sample PMFs of I, B, and P frame sizes are adopted in [26].

The allocated bandwidth for different secondary MTs on the two radio interfaces can be described as

$$\mathcal{B}_{111} = \begin{bmatrix} 1 & 0.5 & 0.375 & 0.25 & 0.125 \\ 1.5 & 1 & 0.75 & 0.5 & 0.25 \end{bmatrix} \quad (23)$$

$$\mathcal{B}_{112} = \begin{bmatrix} 1 & 1.5 & 1.625 & 1.75 & 1.875 \\ 0.5 & 1 & 1.25 & 1.5 & 0.175 \end{bmatrix} \quad (24)$$

$$\mathcal{B}_{211} = \begin{bmatrix} 1.25 & 1.5 & 1.375 & 0.75 & 0.5 \\ 1 & 1.25 & 0.75 & 1.25 & 1.5 \end{bmatrix} \quad (25)$$

and

$$\mathcal{B}_{212} = \begin{bmatrix} 0.75 & 0.5 & 0.625 & 1.25 & 1.5 \\ 1 & 0.75 & 1.25 & 0.75 & 0.5 \end{bmatrix} \quad (26)$$

where the first and second rows in  $\mathcal{B}_{111}$ ,  $\mathcal{B}_{112}$ ,  $\mathcal{B}_{211}$ , and  $\mathcal{B}_{212}$  are the offered bandwidths on the first and second interfaces of different secondary MTs, respectively.  $f_{B_{111}, \dots, B_{212}} = [0.4371 \ 0.2109 \ 0.1217 \ 0.1023 \ 0.1280]$  is the probability that the bandwidths are offered to secondary MTs and each entry in  $f_{B_{111}, \dots, B_{212}}$  corresponds to a column in  $\mathcal{B}_{111}$ ,  $\mathcal{B}_{112}$ ,  $\mathcal{B}_{211}$ , and  $\mathcal{B}_{212}$ . The set of transmission rates supported at each interface is  $\mathcal{R} = \{0.1k, k = 0, 1, \dots, 25\}$  Mbps. With (14),  $\mathcal{R}$  is supported at the two different radio interfaces with different thresholds, for different allocated bandwidths and for different secondary MTs. Each interface has average channel power gain defined by

$$\Omega = \begin{bmatrix} 0.7123 & 0.5031 & 0.4126 & 0.6913 \\ 0.6713 & 0.4852 & 0.4714 & 0.7210 \end{bmatrix}. \quad (27)$$

We evaluate the impact of video quality on available energy at secondary MT in Fig. 3. The average call duration is  $T_c = 20$  minutes, and the call arrival rate to service area is  $\lambda = 0.5$  call/minute. Set  $\varepsilon_q = 0.9$  and  $\varepsilon_c = 0.1$ . The interference threshold has two cases, i.e.,  $I_{ns} = 1 \times 10^{-5}$  W and  $I_{ns} = 5 \times 10^{-5}$  W. From Fig. 3, we observe that CAPS+PAS has the larger video quality than EDFA+PAS. Moreover, the video quality for CAPS+PAS and EDFA+PAS increase with the secondary MT's available energy.



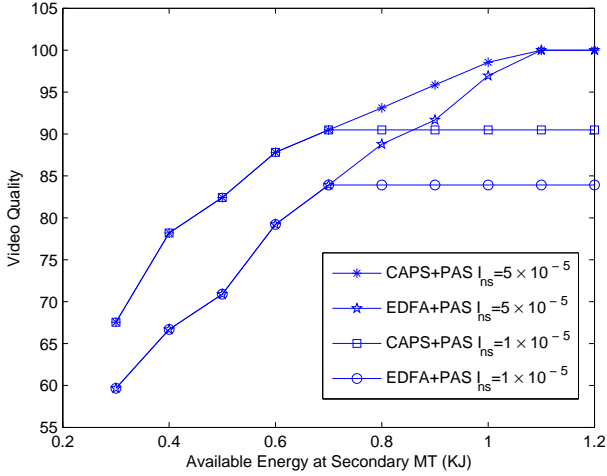


Figure 3. Video quality vs. secondary MT available energy.

This is because CAPS exploits the stochastic video quality characteristic, and allows some video packet with low value to be dropped. Consequently, the video quality for CAPS+PAS improves. For the case  $I_{ns} = 1 \times 10^{-5}$  W, when secondary MT available energy exceeds a special value, video quality remains unchanged. The reason is that the interference power threshold limits the utilization of secondary MT's available energy.

We evaluate the impact of video quality on the interference threshold in Fig. 4. The simulation conditions are  $\varepsilon_q = 0.9$  and  $\varepsilon_c = 0.1$ . The available energy for each secondary MT is  $E = 1$  KJ. The average call duration has two cases, i.e.,  $T_c = 20$  minutes and  $T_c = 60$  minutes. It can be observed that video quality for CAPS+PAS and EDFA+PAS grow with the interference power threshold. This is because increasing the interference power threshold allows secondary MTs to consume more energy to improve the video quality. It can be also see that video quality of EDFA+PAS is smaller than that of CAPS+PAS. The reason is that, in the EDFA+PAS, video packets whose deadline is closer are scheduled earlier, and it is content independent. For the case  $T_c = 60$  minutes, when the interference threshold exceeds a special value, video quality is unchanged. This can be explained that there is not enough energy to improve the video quality.

We evaluate the impact of video quality on the upper bound probability of video call duration in Fig. 5. The simulation conditions are  $\varepsilon_q = 0.9$  and  $I_{ns} = 5 \times 10^{-7}$  W. The available energy of each

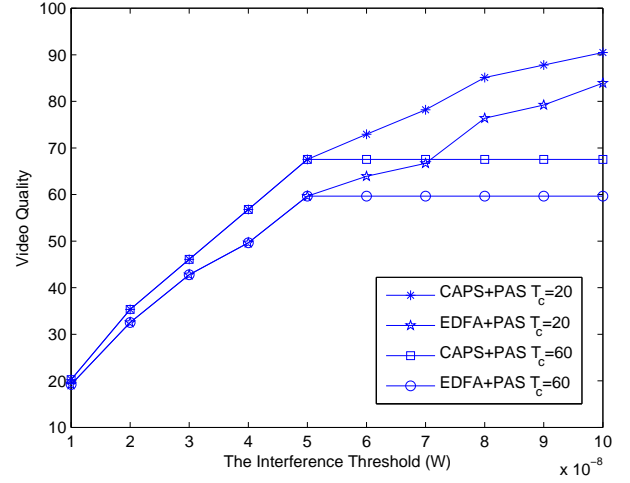


Figure 4. Video quality vs. the interference threshold.

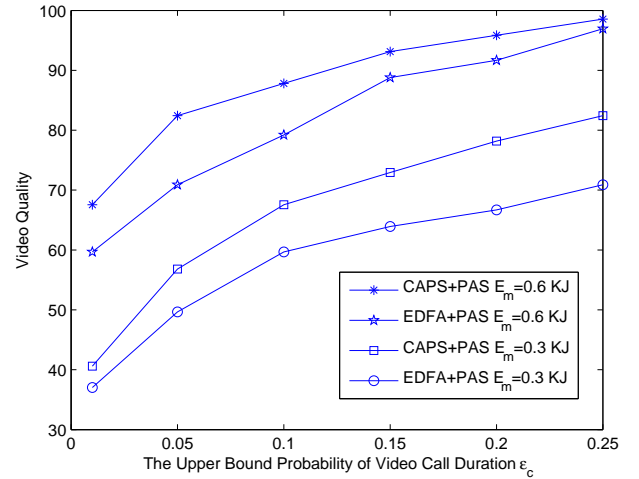


Figure 5. Video quality vs. the upper bound probability of video call duration.

secondary MT has two cases, i.e.,  $E = 0.3$  KJ and  $E = 0.6$  KJ. In Fig. 5, it can be observed that the video quality for two algorithms grows with the upper bound probability of video call duration. Since increasing the upper bound probability of video call duration not only results in the fact that the operation duration per each charging becomes short, but also leads to increase the available energy consumption of each secondary MT.

We evaluate the fairness of video quality for different algorithms in Fig. 6. The average call duration is  $T_c = 40$  minutes. Set  $\varepsilon_c = 0.2$  and  $I_{ns} = 5 \times 10^{-7}$  W. There are two cases for the parameter  $\varepsilon_q$ , i.e.,  $\varepsilon_q = 0.045$  and  $\varepsilon_q = 0.05$ . From Fig. 6, we can see that CAPS+PAS and EDFA+PAS

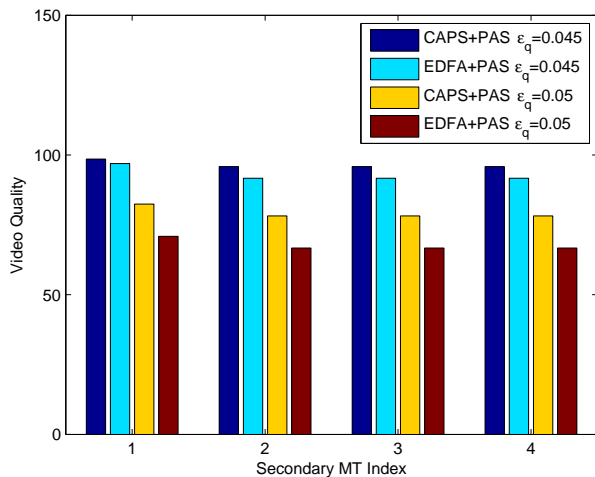


Figure 6. Video quality vs. secondary MT index.

can achieve the better fairness to guarantee the video quality among different secondary MTs. This is because PAS allocates power to guarantee the fairness of video quality among different secondary MTs. Although EDFA+PAS can also achieve the fairness very well, its video quality is smaller than that of CAPS+PAS. From Fig. 3 to Fig. 6, it can be concluded that CAPS+PAS not only improves the video quality, but also guarantees the fairness of video quality among different secondary MTs.

## VI. CONCLUSIONS

In this paper, we investigate the video packet scheduling problem for the sustainable inter-network video transmission over the call duration for cognitive heterogeneous networks. The above optimization problem aims to maximize the lower bound of video quality under the QoS constraints. In order to solve the above stochastic optimization problem, we model the video packet scheduling problem as auction market, and video quality CDF is analyzed. Then, PSO is adopted to adjust the power according to the video stochastic QoS requirement and CSI. The proposed video scheduling framework guarantees the secondary MT to support a required video quality with a certain outage probability over the call duration. Numerical results demonstrate the proposed algorithms can improve the video quality for each secondary MT greatly.

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